

Superior Clamping and Gripping



Product Information

Long-stroke gripper LEG

Flexible. Light. Productive. LEG long-stroke gripper

Electric 2-finger parallel gripper with lightweight profile rail guide and adaptable servo- motor

Field of application

Light long-stroke gripper for flexible and highly dynamic handling of various components. Universal application in clean environments, e.g. in the machine and plant building industry, assembly and handling as well as in the automotive industry.



Advantages - Your benefits

Large moment payloads due to double profiled rail guide suitable for using long gripper fingers

Extremely narrow design for minimal interfering contours

Adaptable drive motor for versatile approach and easy integration into existing control concepts

Position and torque-controlled movement of the gripperFor very flexible gripping of various geometries and types of components

Synchronized but also asynchronous moving of the fingers for various gripping applications

Safety functions such as STO and SLS can be realized by the use of a suitable drive motor and controller

Available for standard robot adaptations according to ISO 9409











Functional description

The two ball-screw spindle drives, which move the base jaw, are driven by one or two servomotors via a toothed belt.

With two drives every jaw can be moved individually from

each other. During the actuation with a servomotor, a coupling synchronizes the right-to-left and the left-to-right spindle with each other.



- Recirculating ball bearing guide
 precise gripping due to high-amperage smoothly
 running recirculating ball bearing guide
- ② Base Jaw for the connection of workpiece-specific gripper fingers
- 3 Housing weight-optimized due to FEM and topology examination
- Winematics high moment payloads and accuracy due to the ball screw
- 5 Motor installation space for various motors
- 6 Linear guide heavy-duty for high moment loads and long top jaws

CAD data, operating manuals and other current product documents can be found online.

Application examples

Handling of cardboard packaging



Basic version of LEG

- 1 LEG 2-finger long-stroke gripper
- 2 Gripper fingers

Gripping system solution for asynchronous handling of cardboard packaging



The LEG gripping system solution with two asynchronous grippers accommodates multiple cardboard packaging in successive sequences. The higher-level asynchronous gripper serves only for adjusting the inside micrometer.

- LEG 2-finger long-stroke gripper, asynchronous version
- 2 LEG 2-finger long-stroke gripper, asynchronous version

Gripping system solution for synchronous handling of cardboard packaging



The LEG gripping system solution with two synchronous grippers is used for handling multiple cardboard packaging at the same time. The higher-level asynchronous gripper serves only for adjusting the inside micrometer.

- LEG 2-finger long-stroke gripper, asynchronous version
- 2 LEG 2-finger long-stroke gripper, synchronous version



LEG with palletizing option - pallet handling



Gripping system solution with palletizing option for handling pallets, clipboards and cardboard packaging

- LEG 2-finger long-stroke gripper, synchronous version
- 2 Swiveling arm for form-fit gripping of pallets

LEG with palletizing option - handling cardboard packaging



- LEG 2-finger long-stroke gripper, synchronous version
- 2 Gripper fingers

LEG with palletizing option - handling of clipboards



- LEG 2-finger long-stroke gripper, synchronous version
- Vacuum suction cup

General notes about the series

Operating principle: Spindle drive

Housing material: Aluminum alloy, coated

Base jaw material: hard-anodized, high strength

aluminum

Actuation: electrically via an adaptable servo drive

Warranty: 24 months

Scope of delivery: Enclosed pack with centering sleeve and centering pins, assembly and operating manual with Declaration of Incorporation. Depending on the variant, operation of the gripper requires a motor add-on kit, a servo motor, and a suitable controller. They are not included in the scope of delivery and must be ordered separately.

Gripping force: is the arithmetic total of the gripping force applied to each gripper jaw at distance P (see illustration).

Finger length: measured from the screw surface of the base jaw in the direction of the main axis. Failure to comply with the max. permissible finger length will result in increased wear.

Repeat accuracy: is defined as the spread of the end position during 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: When gripping, the speed must be adapted as described in the operating manual so that the closing and opening times can increase. The times specified are only the movement times of the base jaws at max. speed, max. acceleration without electrical restrictions, and observance of the maximum permissible masses per finger.

Motor torque: Required motor torque may be permanently applied to achieve the maximum gripping force.



Application example

Gripping system solution comprising three electric grippers for the handling of a wide variety of workpieces

- LEG 2-finger long-stroke gripper, asynchronous version
- 2 LEG 2-finger long-stroke gripper, synchronous version
- 3 Adapter flange

SCHUNK offers more ...

The following components make the product LEG even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.





Finger change system (on request)

① For more information on these products can be found on the following product pages or at schunk.com. Please contact us: SCHUNK technical hotline +49-7133-103-2696

Options and special information

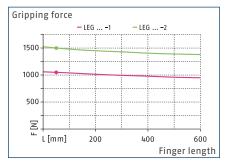
Flexible in motor and controller selection: The electrical control is carried out via an adaptable servo drive using common standard controller like Bosch or Siemens

Easy integration: The easy integration into the control system is ensured by the possibility of attaching a common servomotor.

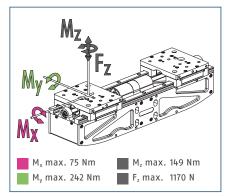
Identical control: Like a normal servo axis, the gripper can be directly controlled and interpolated with existing axes. **Complete solutions:** On request, SCHUNK can supply complete drive solutions including motor, gears, controller, and cables.



Gripping force



Finger load



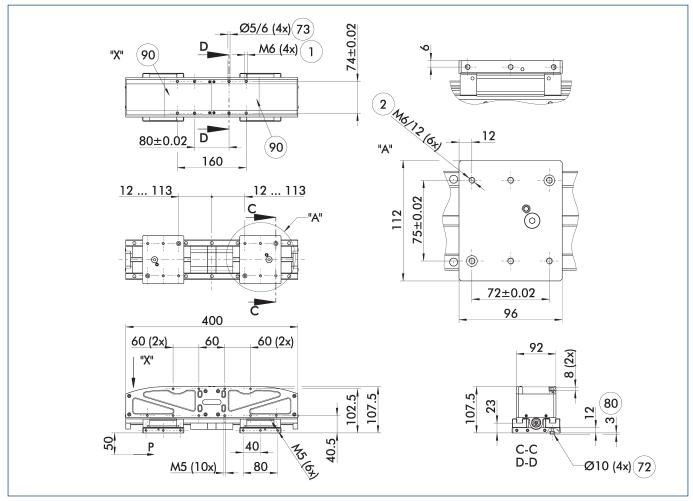
The specified torques and forces are static values, apply for each base jaw, and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself.

Technical data

Description		LEG 400-1-15-2-10X3-B	LEG 400-2-15-2-10X3-B				
ID		0308040	0308041				
General operating data							
Stroke per jaw	[mm]	101	101				
Min./max. gripping force	[N]	300/1050	300/1500				
Closing/opening time	[s]	0.55/0.55	0.55/0.55				
Max. permissible speed (positioning)	[mm/s]	276	276				
Max. permissible speed (gripping)	[mm/s]	10	10				
Recommended workpiece weight	[kg]	5.25	7.5				
Repeat accuracy	[mm]	0.05	0.05				
Max. permissible finger length	[mm]	600	600				
Max. permissible mass per finger	[kg]	10	10				
motor moment required	[Nm]	1	0.75				
Max. drive speed	[1/min]	4000	4000				
Weight	[kg]	5.4	5.4				
Min./max. ambient temperature	[°C]	5/55	5/55				
Protection class IP		20	20				
Noise emission	[dB(A)]	<70	<70				
Options and their characteristics							
Version with a motor		LEG 400-1-15-2-10X3-MSM031B	LEG 400-2-15-2-10X3-MSM031B				
ID		0308042	0308043				
Weight	[kg]	6.9	8.3				

① Motors are not included in the purchase price in the base variant. Please ask us for details about the integration of your motor type.

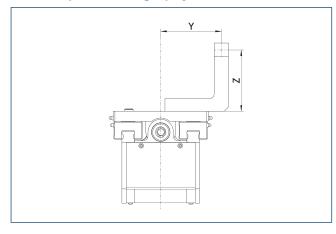
Main view

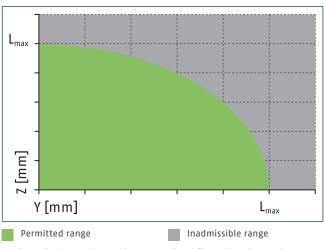


The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

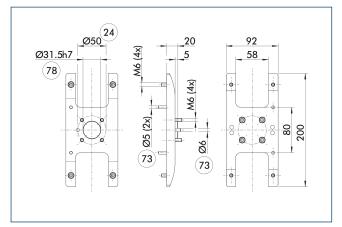
- 1 Gripper connection
- 2 Finger connection
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Plug connector of the individual motor

Maximum permitted finger projection





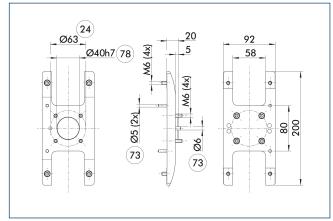
 L^{max} is equivalent to the maximum permitted finger length, see the technical data table



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID
ISO flanges	
ADF 050	0308090

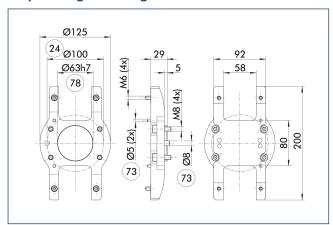
Adapter flange according to ISO-9409-1-063



- 24) Bolt circle
- (78) Fit for centering
- 73 Fit for centering pins

Description	ID
ISO flanges	
ADF 063	0308091

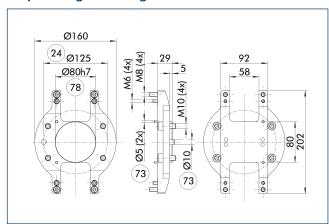
Adapter flange according to ISO-9409-1-100



- 24) Bolt circle
- 78 Fit for centering
- (73) Fit for centering pins

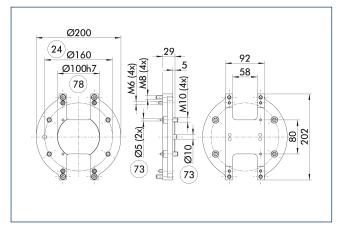
Description	ID							
ISO flanges								
ADF 100	0308092							

Adapter flange according to ISO-9409-1-125



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID	
ISO flanges		
ADF 125	0308093	



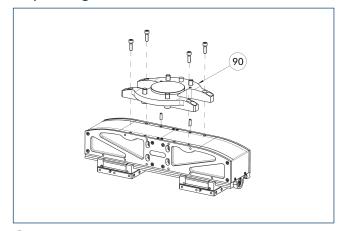
24 Bolt circle

78 Fit for centering

73 Fit for centering pins

Description	ID
ISO flanges	
ADF 160	0308094

Adapter flange

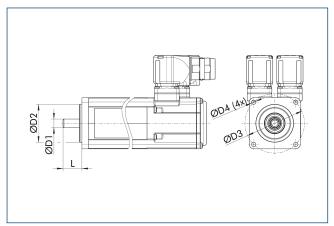


90 Adapter flange

 $\label{prop:constraints} \mbox{Adapter flange for connection of additional SCHUNK components or customized attachments.}$

Description	ID
ISO flanges	
ADF 050	0308090
ADF 063	0308091
ADF 100	0308092
ADF 125	0308093
ADF 160	0308094

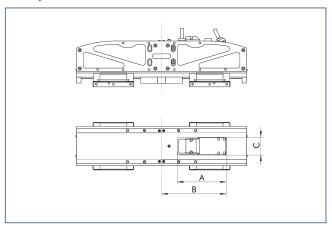
Motor add-on kit



The basic version without a drive motor (version B) can be equipped with the corresponding motor using a motor attachment kit. The motor itself is not part of the attachment kit, and must be provided by the customer.

Description	ID	D ₁	D ₂	\mathbf{D}_3	D ₄	L min/
						max
		[mm]	[mm]	[mm]		[mm]
Motor add-on kits						
MAS-LEG 09-050-070-M05	1331139	9	50	70	M5	15/21
MAS-LEG 11-050-070-M04	1331129	11	50	70	M4	15/21

Cover plate

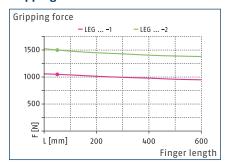


The cover plate protects the gripper against external influences up to protection class IP20. The basic version without a drive motor requires one cover plate for each motor.

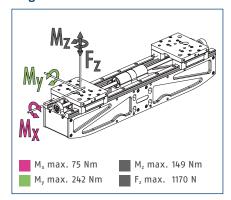
Description	ID	Α	В	C
		[mm]	[mm]	[mm]
Cover plate				
ADB-LEG 400-000-000-000	1331174	0	0	0
ADB-LEG 400-115-152-042	1331172	115	152	42



Gripping force



Finger load



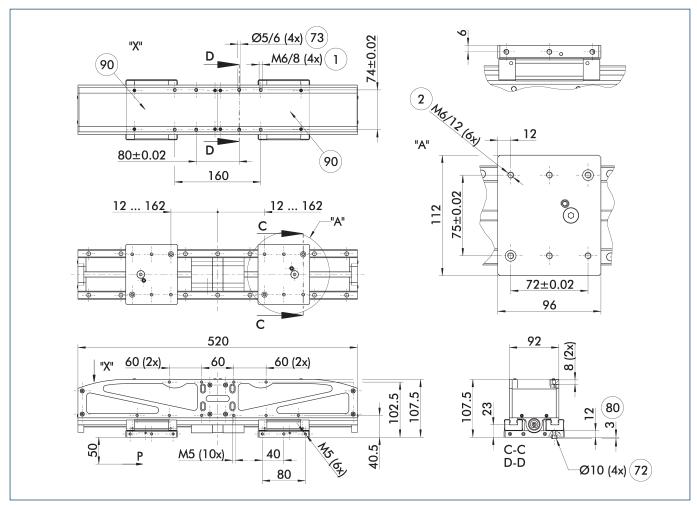
The specified torques and forces are static values, apply for each base jaw, and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself.

Technical data

Description		LEG 520-1-15-2-10X3-B	LEG 520-2-15-2-10X3-B		
ID		0308050	0308051		
General operating data					
Stroke per jaw	[mm]	161	161		
Min./max. gripping force	[N]	300/1050	300/1500		
Closing/opening time	[s]	0.73/0.73	0.73/0.73		
Max. permissible speed (positioning)	[mm/s]	276	276		
Max. permissible speed (gripping)	[mm/s]	10	10		
Recommended workpiece weight	[kg]	5.25	7.5		
Repeat accuracy	[mm]	0.05	0.05		
Max. permissible finger length	[mm]	600	600		
Max. permissible mass per finger	[kg]	10	10		
motor moment required	[Nm]	1	0.75		
Max. drive speed	[1/min]	4000	4000		
Weight	[kg]	6.4	6.4		
Min./max. ambient temperature	[°C]	5/55	5/55		
Protection class IP		20	20		
Noise emission	[dB(A)]	<70	<70		
Options and their characteristics					
Version with a motor		LEG 520-1-15-2-10X3-MSK030B	LEG 520-2-15-2-10X3-MSK030B		
ID		0308052	0308053		
Weight	[kg]	8.2	9.9		

① Motors are not included in the purchase price in the base variant. Please ask us for details about the integration of your motor type.

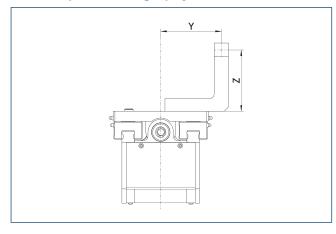
Main view

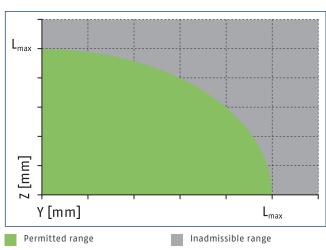


The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

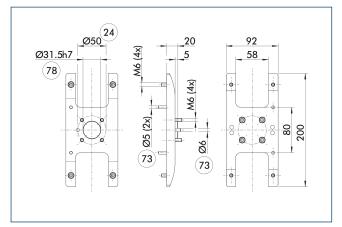
- 1 Gripper connection
- 2 Finger connection
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Plug connector of the individual motor

Maximum permitted finger projection





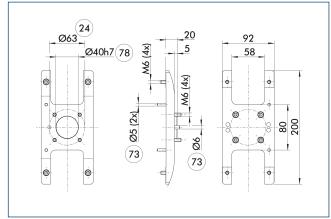
 L^{max} is equivalent to the maximum permitted finger length, see the technical data table



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID
ISO flanges	
ADF 050	0308090

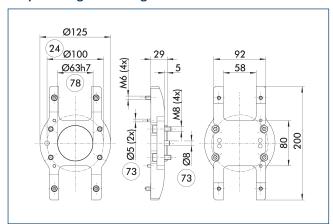
Adapter flange according to ISO-9409-1-063



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID	
ISO flanges		
ADF 063	0308091	

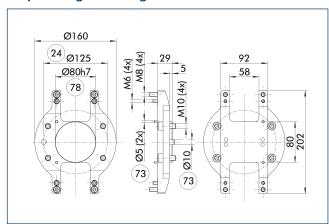
Adapter flange according to ISO-9409-1-100



- 24) Bolt circle
- 78 Fit for centering
- (73) Fit for centering pins

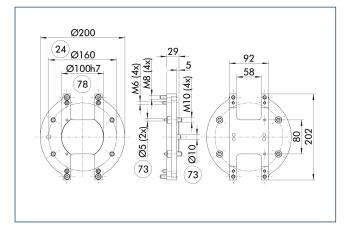
Description	ID							
ISO flanges								
ADF 100	0308092							

Adapter flange according to ISO-9409-1-125



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID	
ISO flanges		
ADF 125	0308093	



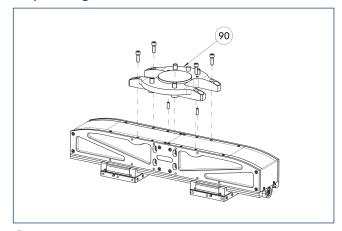
24 Bolt circle

78 Fit for centering

73 Fit for centering pins

Description	ID
ISO flanges	
ADF 160	0308094

Adapter flange

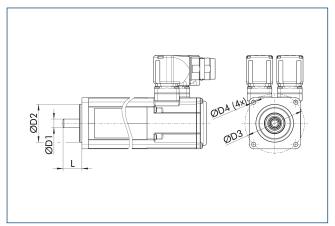


90 Adapter flange

Adapter flange for connection of additional SCHUNK components or customized attachments.

Description	ID
ISO flanges	
ADF 050	0308090
ADF 063	0308091
ADF 100	0308092
ADF 125	0308093
ADF 160	0308094

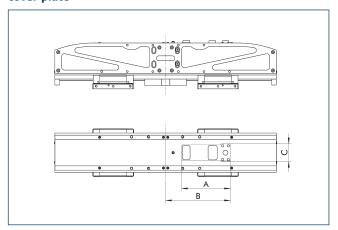
Motor add-on kit



The basic version without a drive motor (version B) can be equipped with the corresponding motor using a motor attachment kit. The motor itself is not part of the attachment kit, and must be provided by the customer.

Description	ID	D ₁	D ₂	D ₃	D ₄	L min/ max
		[mm]	[mm]	[mm]		[mm]
Motor add-on kits						
MAS-LEG 09-040-063-M05	1331148	9	40	63	M5	15/21
MAS-LEG 09-050-070-M04	1331135	9	50	70	M4	15/21
MAS-LEG 09-050-070-M05	1331139	9	50	70	M5	15/21
MAS-LEG 11-050-070-M04	1331129	11	50	70	M4	15/21

Cover plate

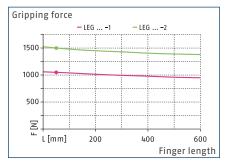


The cover plate protects the gripper against external influences up to protection class IP20. The basic version without a drive motor requires one cover plate for each motor.

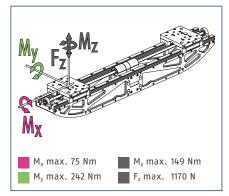
Description	ID	Α	В	C
		[mm]	[mm]	[mm]
Cover plate				
ADB-LEG 520-000-000-000	1331187	0	0	0
ADB-LEG 520-065-210-060	1331176	65	210	60
ADB-LEG 520-100-200-059	1331182	100	200	59
ADB-LEG 520-110-203-059	1331184	110	203	59
ADB-LEG 520-115-152-042	1331179	115	152	42



Gripping force



Finger load

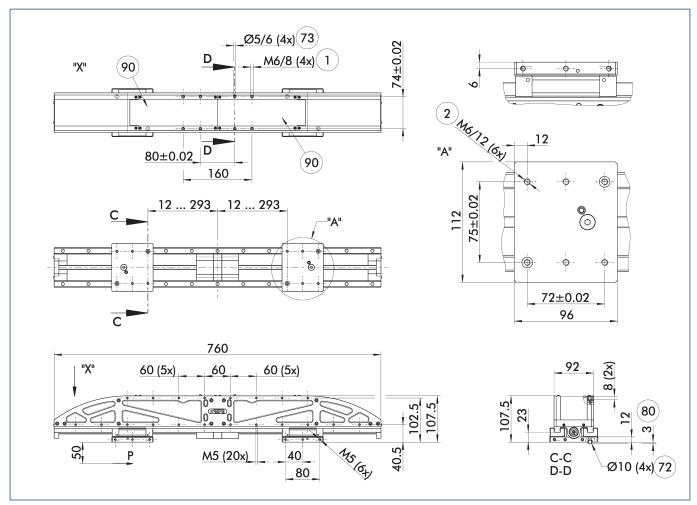


Technical data

Description		LEG 760-1-15-2-10X3-B	LEG 760-2-15-2-10X3-B
ID		0308060	0308061
General operating data			
Stroke per jaw	[mm]	281	281
Min./max. gripping force	[N]	300/1050	300/1500
Closing/opening time	[s]	1.2/1.2	1.2/1.2
Max. permissible speed (positioning)	[mm/s]	276	276
Max. permissible speed (gripping)	[mm/s]	10	10
Recommended workpiece weight	[kg]	5.25	7.5
Repeat accuracy	[mm]	0.05	0.05
Max. permissible finger length	[mm]	600	600
Max. permissible mass per finger	[kg]	10	10
motor moment required	[Nm]	1	0.75
Max. drive speed	[1/min]	4000	4000
Weight	[kg]	7.9	7.9
Min./max. ambient temperature	[°C]	5/55	5/55
Protection class IP		20	20
Noise emission	[dB(A)]	<70	<70
Options and their characteristics			
Version with a motor		LEG 760-1-15-2-10x3-MSK030B	LEG 760-2-15-2-10x3-MSK030B
ID		0308062	0308063
Weight	[kg]	9.7	11.4

① Motors are not included in the purchase price in the base variant. Please ask us for details about the integration of your motor type.

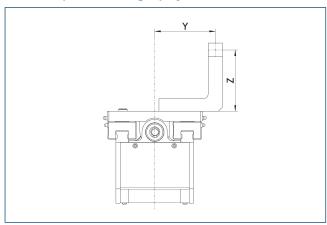
Main view

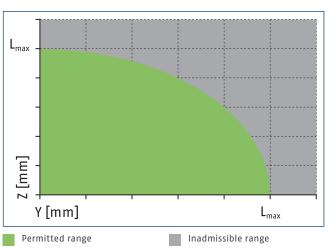


The drawing shows the basic version of the gripper without dimensional consideration of the options described below.

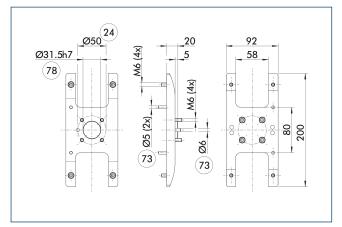
- 1 Gripper connection
- 2 Finger connection
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Plug connector of the individual motor

Maximum permitted finger projection





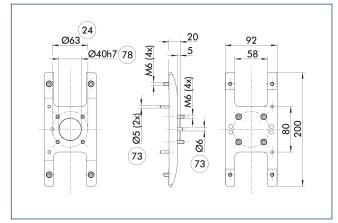
 L^{max} is equivalent to the maximum permitted finger length, see the technical data table



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID
ISO flanges	
ADF 050	0308090

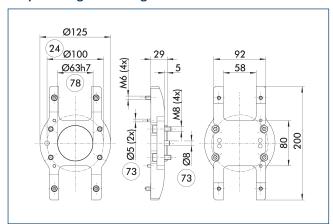
Adapter flange according to ISO-9409-1-063



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID	
ISO flanges		
ADF 063	0308091	

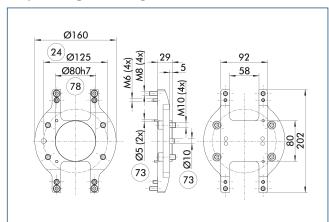
Adapter flange according to ISO-9409-1-100



- 24) Bolt circle
- 78 Fit for centering
- (73) Fit for centering pins

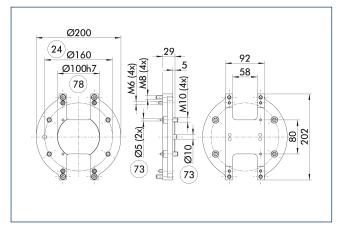
Description	ID	
ISO flanges		
ADF 100	0308092	

Adapter flange according to ISO-9409-1-125



- 24) Bolt circle
- 78 Fit for centering
- 73 Fit for centering pins

Description	ID	
ISO flanges		
ADF 125	0308093	



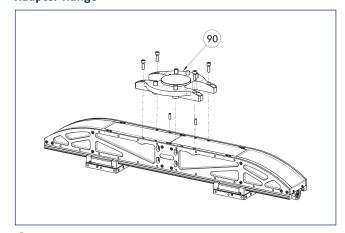
24 Bolt circle

78 Fit for centering

73 Fit for centering pins

Description	ID
ISO flanges	
ADF 160	0308094

Adapter flange

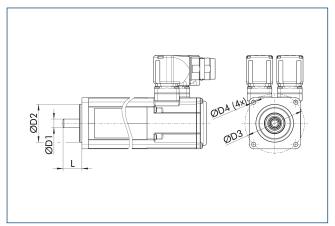


90 Adapter flange

 $\label{prop:constraints} \mbox{Adapter flange for connection of additional SCHUNK components or customized attachments.}$

Description	ID
ISO flanges	
ADF 050	0308090
ADF 063	0308091
ADF 100	0308092
ADF 125	0308093
ADF 160	0308094

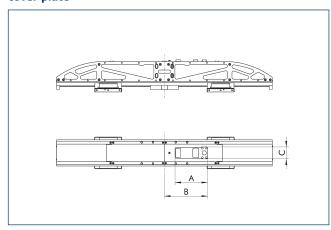
Motor add-on kit



The basic version without a drive motor (version B) can be equipped with the corresponding motor using a motor attachment kit. The motor itself is not part of the attachment kit, and must be provided by the customer.

Description	ID	D ₁	D ₂	D ₃	D ₄	L min/ max	
		[mm]	[mm]	[mm]		[mm]	
Motor add-on kits							
MAS-LEG 09-040-063-M05	1331148	9	40	63	M5	15/21	
MAS-LEG 09-050-070-M04	1331135	9	50	70	M4	15/21	
MAS-LEG 09-050-070-M05	1331139	9	50	70	M5	15/21	
MAS-LEG 11-050-070-M04	1331129	11	50	70	M4	15/21	

Cover plate



The cover plate protects the gripper against external influences up to protection class IP20. The basic version without a drive motor requires one cover plate for each motor.

Description	ID	A	В	C			
		[mm]	[mm]	[mm]			
Cover plate							
ADB-LEG 760-000-000-000	1331191	0	0	0			
ADB-LEG 760-051-205-060	1331188	51	205	60			
ADB-LEG 760-095-205-059	1331190	95	205	59			
ADB-LEG 760-115-152-042	1331189	115	152	42			

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